Surphaser



Prerequisites

Before adding and running a Surphaser Scanner in SA, the appropriate USB drivers must first be installed.

Download the operating system-specific Surphaser drivers from ftp:// ftp.kinematics.com/pub/SA/Install/Driver%20Downloads/Scanners/ Surphaser/. (*note the "USB Driver" is for Windows 10).

- Unzip the drivers into a known location. Example: C:\ DrvWinUsb
- 2. Plug in the Surphaser USB cable to the PC. Windows should recognize the USB device and automatically locate the drivers and install them. If this is performed correctly, the Surphaser scanner will be presented in your Device list (Figure 7-3).



If windows does not automatically acquire the driver then go to **Control Panel//System//Device Manager** locate the unknown USB device and

Figure 7-3. The Device list.

(under Human Interface Devices) and right-click on it. Select Update Driver and direct the search to the folder in which you placed the USB drivers.

You will also need to locate the Rpr file for your particular scanner which is the parameter file and should be supplied with the instrument.

Running the Surphaser

1. Add a Surphaser to SA via Instrument>Add or using the ℜ icon. Select the Surphaser Scanner or Surphaser 10 Scanner and press Add Instrument (Figure 7-4).



- 2. Run the instrument interface module under Instrument>Run Interface Module and choose Surphaser.
- **3.** When the instrument interface opens for the first time you will need to browse to the Options tab and update the path to the Rpr file (Figure 7-5).



| | Scan Options Log 2D Azimuth | – 🗆 X |
|---|---|---|
| Figure 7-5. Options Tab of the Surphaser Interface | Scan Options ✓ Find Azimuth Ref Before the First Scan □ Full Volume Scan From Current Position □ Mirror Down After Each Scan ✓ Return to Original Position After Scan | Preview Scan Options ☑ Delete Preview Scan After Selection □ Auto Export Preview Bitmap |
| | Detailed Log SoundOn On Rpr Update Save Options Update Save Status: NoScannerConnected - A::0 - Surphas | Fans On Modify |

The Rpr file needs to be in the following directory: C:\Users\[user]\ AppData\Roaming\NRK\SA Surphaser 3.12. Each scanner has it's own Rpr file so it is possible to have multiple files in this same directory. You will need to set this path by selecting Open once for each file. This will register the Rpr file with the Scanner's internal list (in an XML file also in this directory). From then on any of the registered scanners can be plugged in and used and the correct Rpr file will be found for it automatically.

After the first connection a user should be able to simply plug in the scanner, add a new instrument model and press the Running Man icon *T* to connect

Scanning with the Surphaser

The SA Surphaser Interface provides a lot of options but a basic scan can be performed as follows:

- Verify the Scan Density and Processing Option settings are set 1. at reasonable levels.
- 2. Check the ouput file name (Collection & Cloud Name) for the cloud is set how you would like it to appear in SA and check that the Send to SA When Done Scanning check box is enabled.
- 3. Adjust your scan region as desired or set it to a Full Volume scan
- When satisfied press the scan button $ec{O}$ 4.



Instrument Specifics

The instrument interface provides a detailed panel style control for driving the scanner. It is composed of a set of master control buttons and 5 tabs to easily set up and process a scan (Figure 7-6).

| | 5 SA Surphaser | - • × |
|------------------------------------|---|--|
| | Scan Ontions Log 2D Azimuth | |
| | Scanner Info | Qutout Filename (btx and ing) |
| | Scanner: 7001 is On | Scan_17_05_18_15_00.c3d |
| | Config: StandardConfig_1pass_HQ ···· | Collection Cloud Name |
| | Scan Info Cloud Pts (est) 2557440 | A ::: SurphCloud Set Cloud Group Group (For Marker Points) |
| | Time 1m, 4s Size (MB, est) 38.89 Mb ReCalc | from Output Filename SurphMarkers |
| | Scan Density O Low: 24 LPD x 24 PPD | Scan Region |
| | O Normal: 30 LPD x 30 PPD Change density | Sector Scan, Azimuth: |
| | User: 8 LPD x 24 PPD | From: 0 120 + |
| Figure 7-6. SA Surphaser Interface | Processing Options | |
| - | Minimum Distance 0.00 t | Sector Sides |
| | Maximum Distance 656.00 t | ○ Front and Back |
| | Min Intensity 100 in un | Vertical Range |
| | □ Incidence Angle 5.0 | Low: -40 💼 High: 25 💼 deg |
| | Markers Search Rectangular NMarkers: 6 ÷ | Saved Parameter Sets |
| | Search Spherical | Select Default ~ |
| | RMin: 1.000 RMax: 12.500 in | |
| | ☑ Send to SA When Done Scanning | Save Current Parameters |
| | Send a Scan to SA | Delete Selected Clear All |
| | Status:Connected, HardwareInitialized - A::0 - Surphaser Scan Tab. Which provides | direct configuration of the scan to |
| | be performed. | J |
| | Options Tab. Which provide | de a set of controls and preferences |
| | for scapping and scap prov | views that shouldn't need to be ed- |
| | ite dans and such a sig (Figure | |
| | Ited on a regular basis (Fig | ure 7-5). |
| | Log Tab. This page provid | les a running record of the scanner |
| | activity and the associated | file names and directories used |
| | • 2D Tab. This page provide | es a preview image of the scan and |
| | allows for region selection | and re-scan control. |
| | Azimuth Tab. Provides me rest control. | ove control and Azimuth zero point |
| | | |
| Scan Controls | | |
| | The Scan tab provides the primar | y scan controls: |
| | | - |
| Scanner & Scan Info | | |
| | The scanner section provides identified to the scanner section provides identified (Figure 7-7) | ntification information and configu- |
| | | |

Figure 7-7. Surphaser Interface showing the tabs and scanner information sections

| Scanner Info | | | |
|--|---|-------------------|--|
| Scanner: 7001 is On Config: StandardConfig_1pass_HQ ···· | | | |
| Scan Info Cloud Pts (est) 10 Time 80(sec) | 00000 Size (MB, est) 200 | 5K ReCalc | |
| Scan Density Low: Normal: User: | 24 LPD x 24 PPD 30 LPD x 30 PPD 40 LPD x 40 PPD | Change density | |

This section provides a preview of the scan that would be generated with the current settings. This can be very helpful because it provides advance knowledge of the number of points being requested, the time required to generate the scan and the resulting file size that would be generated.

Scan Density

The scan density can be defined either using **Low** or **Normal** density as well as using a **Custom** value set through the **Change** density button. The **Lines Per Degree (LPD)** and **Points Per Degree (PPD)** defines a grid density that can be set at a prescribed distance, and doing so will present an estimate for the Scan Time and Scan File Size.

To set the density at a given range, enter the **Point Spacing** you would like to have at a give distance and press the <u>Set</u> button. This will recompute the user defined density setting for you (Figure 7-8).

SPATIALANALYZER USER MANUAL

| | Horizontal Density(LPD) | Vertical Density(PPD) |
|----------------------------|--|--|
| | 21 🗧 | 23 🗧 |
| | Point Spacing 1 in. at | 100 ft. Set |
| | Voxelization | |
| | Voxel Size 0.35 in. Mi | n Pts/Voxel 4 |
| | # Pts to Voxelize 200000 | □ Send Voxelized Cloud |
| Figure 7-8 Change density | Restore Defaults | ☑ Send Scanned Cloud |
| controls dialog. | | |
| | Sector to econ | Eul |
| | Scan Time | 2m 59s |
| | Lines per Circle | 7540 |
| | Points per mirror | 8333 |
| | Full Number of Points | 28342207 |
| | Scan File Size | 420.93 |
| | Density Mode User | |
| | Equal Grid Aspect Ratio | D |
| | ОК | Cancel |
| | | |
| Voxelization | | |
| | Scans can be sent to SA at full re | solution and/or using a voxelized |
| | sub-sampling approach. Simply c | heck the options as to which data |
| | foramt to import into SA. Much lik | e voxelizing a cloud directly withir |
| | SA, the Voxel Size determines the vo | lume of data processed to produce |
| | a single point, the Min Pts/Voxel de | etermines the required number of |
| | points per voxel for a point to reta | ined, providing an outlier rejectior |
| | option. The # Pts to Voxelize determi | nes the batch processing size. |
| Cloud Name Controls | | |
| | The cloud name control section is | s used to define the base name of |
| | the point cloud saved within the | SA job file (Figure 7-9). It will also |
| | be used to name the voxel cloud, b | by appending "_vox" to the entered |
| | cloud and using it for the target point group if needed. | |

CHAPTER 7 • MEASURING WITH ROOM SCANNERS

| | Output Filename (btx and jpg) | |
|--------------------------------|---|---|
| | Scan_17_05_18_15_00.c3d | |
| | Collection | Cloud Name |
| Figure 7-9. Cloud Name Control | A :: | SurphCloud |
| | Set Cloud Group from Output Filename | Group (For Marker Points) SurphMarkers |

The collection and cloud name can be entered here as well as the group name for the target markers. The *Set Cloud Group from Output Filename* checkbox can be used to ensure that the saved scan files or imported scan file names are used and synchronized with the cloud names within SA.

Processing Options

Processing filters are applied as a post processing operation following the scan and prior to passing the scan data to SA (Figure 7-10).

| Processing Options | |
|--------------------|---------------------|
| Minimum Distance | 0.00 ft |
| Maximum Distance | 656.00 f t |
| 🗹 Min Intensity | 100 • un |
| Max Intensity | 20000 • un |
| ✓ Incidence Angle | 5.0 • deg |
| Markers | |
| Search Rectangular | NMarkers: 100 |
| Search Spherical | |
| RMin: 0.500 | ▲ RMax: 10.000 ▲ in |

- Distance filter. Minimum and Maximum Distance setting can be enabled to remove points from the scan that are beyond these thresholds.
- Intensity filter. Minimum and Maximum Intensity setting can be enabled to remove points from the scan that are beyond these thresholds.
- Incidence Angle. Defines an acceptance threshold for scan angle which describes the minimum incidence angle accepted.
- Markers. Both rectangular (checkerboard) and spherical markers can be detected from the scan automatically as part of the post scan processing. The NMarkers numeric field provides a convenient way to identify how many markers should exist in and be extracted from the scan. Only the best specified num-

Figure 7-10. Scan Processing Options

ber of targets in the data set will then be returned. The RMin and RMax controls can be used to restrict target detection to with a size range (for both target types).



 Sector Sides. The scan can be restricted to only use the front or back face of the scanner as well as both. With Front and Back checked the scan includes a full path from low over the vertical to the back low point in a full arc. Vertical Range. When either front or Back are set the vertical range controls become enabled and set the upper and lower limits of the scan.

These values can also be easily populated by doing a quick overview scan and then selecting the region you would like to scan graphically from the image on the 2D Tab (Figure 7-13). A prompt will provide an easy way to update the existing Azimuth and Vertical Range settings from the selected region. This region can then be save as part of a Parameter Set. More than one region will remain selected for reference but only a single scan region can be used at one time.





Parameter Sets

Configuration settings for a scan can be named and saved as part of a *Parameter Set*. These include the following parameters:

- Name
- Scan Density, LPD (Lines per Degree), and PPD (Points per Degree)
- Distance, Intensity and Incidence Angle Filters with options to turn either on or off.

- Markers, Search Rectangular (true or false), Search Spherical (true or false), *NMarkers* (number of markers), *RMin* (minimum marker size), *RMax* (max marker size)
- Full Volume or Sector Scan. Sector Scan is the same as before, with settings for the vertical and horizontal ranges. Full Volume is a full 360 deg. scan.
- Sector Scan Range, Azimuth From, To (degrees), and Elevation Low, High (degrees).
- Front, Back, Front and Back. Previous versions of the Surphaser interface only allowed either the front face or both. Now, a Sector Scan can include only the back face as well.

Parameter sets are saved in the persistence file. To update a saved parameter set (rather than create a new one with a small change), press Save Current Parameters and give it the same name as the existing parameter set you wish to update. This will overwrite the existing parameter set and update it.

Importing Saved Scan Files

At the bottom of the Scan tab is a Send a Scan to SA button. This button provides direct access to importing pre-existing scan files of *.btx, and *.ptx formats (Figure 7-14).

 Figure 7-14. Controls for Importing Scans
 Send to SA When Done Scanning

 Send a Scan to SA
 Send a Scan to SA

The Send to SA When Done Scanning option is used to trigger an import as soon as a scan completes. Scan files (.c3d, .btx) as well as preview images (.jpg) and text files of the marker coordinates (.txt) are saved in the C:\Users\[User]\AppData\Roaming\NRK\SA Surphaser 3.12\Scan directory as part of the scanning process. These file may need to be periodically purged to keep the size down.

Working Offline

In addition to importing existing saved san files using the <u>Send a Scan</u> to <u>SA</u> button, <u>Parameter Sets</u> can be created offline through the simulation interface. To start the Surphaser interface in simulation (without hardware) do the following:

- 1. Select Instrument>Run Interface Module
- 2. Then select the **Surphaser** interface from the list of interfaces
- **3.** In the Surphaser Connection dialog first pick the instrument model then un-check the Connect Scanner check box, and press OK.

Parameter sets are saved in the persistence file located in C:\Analyzer Data\Persistence. The SASurphaserSettings.bin file contains the saved Parameter Sets and can be distributed to different machines.

Azimuth Designation

The Surphaser currently does not have an absolute zero location for the Azimuth (horizontal angle). This means that starting a scan from a designated azimuth value will not necessarily return the same results if you turn off the scanner and then reconnect later. It can also drift or be rest during a connection. For this reason, the Azimuth tab offers the users the ability to reset the zero location or move the instrument to a preset value (Figure 7-15).



If the azimuth changes for any reason it is advisable to add an additional instrument station to SA. This can be done by right-clicking on the instrument and selecting **Jump Instrument to New Location**. This will make it easier to align the scans.

At this point, the best practice is to scan common markers in order to precisely locate the new station to the old. If the Azimuth control is used, then a test scan will reveal how well the reset azimuth matches the old. Be sure the newly added station is in the same position as the old in this case.

Measurement Plan (MP) support

SA provides comprehensive support for automation purposes. You can define regions from measurements within SA, designation pe-

Figure 7-15. Azimuth Tab of the Surphaser Interface

rimeters and scan them as needed using predefined Parameter Sets called by name. However, the azimuth zero position can and will change so that needs to be accounted for.

- Set Instrument Group and Target. The "Point Name" argument will set the Collection and Cloud names, as well as the group name for found targets, and the voxel cloud name (if set to send).
- Configure and Measure. The "Point Name" argument will set the Collection and Cloud names, as well as the group name for found targets, and the voxel cloud name (if set to send). The "Measurement Mode" argument specifies the Saved Parameter Set (measurement profile). If the profile is not found, the command will fail if the User Interaction Mode is set to Silent. Otherwise, you'll be asked if you want to use the current settings. If "Measure Immediately" is false, the command will simply set the profile selected if it is found. The "Timeout in Seconds" is ignored, since scan time can vary quite a lot, depending on scan paramters.
- Scan within perimeter. Ensure that the azimuth has not drifted on the scanner since the definition of the "Scan perimeter name". You can use the [Azimuth] tab in the interface to control the zero location, or simply use scanned [Markers] to locate the instrument. The "Parameter set name" specifies the Saved Parameter Set (measurement profile). If the profile is not found, this command will proceed with current settings if the User Interaction Mode is set to Silent. Otherwise, you'll be asked if you want to use the current settings.
- Instrument Operational Check. Instrument Operational Check "Send Scan to SA [path]". Supports importing of both *.ptx and binary *.btx files. Also the command "Find Zero" is available to return as closely as possible to the Azimuth zero point.